

Density, distribution, and activity of the ocelot *Leopardus pardalis* (Carnivora: Felidae) in Southeast Mexican rainforests

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Abstract: The ocelot *Leopardus pardalis* is of particular significance in terrestrial communities due to its ecological role within the group of small-sized felids and as a mesopredator. However, despite the reduction of ocelot habitat in Southeast Mexico, there are still very few ecological studies. This research aimed to contribute with some ecological aspects of the species in this region. For this, 29 camera trap stations were established in a rain forest in Los Chimalapas (an area of 22km²) during a two years period (March 2011-June, 2013), in Oaxaca state, Southeast Mexico. Data allowed the estimation of the population density, activity pattern, sex ratio, residence time, and spatial distribution. Population density was calculated using Capture-Recapture Models for demographically open populations; besides, circular techniques were used to determine if nocturnal and diurnal activity varied significantly over the seasons, and Multiple Discriminant Analysis was used to determine which of the selected environmental variables best explained ocelot abundance in the region. A total of 103 ocelot records were obtained, with a total sampling effort of 8 529 trap-days. Density of 22-38 individuals/100km² was estimated. Ocelot population had a high proportion of transient individuals in the zone (55%), and the sex ratio was statistically equal to 1:1. Ocelot activity was more frequent at night (1:00-6:00h), but it also exhibited diurnal activity throughout the study period. Ocelot spatial distribution was positively affected by the proximity to the village as well as by the amount of prey. The ocelot population here appears to be stable, with a density similar to other regions in Central and South America, which could be attributed to the diversity of prey species and a low degree of disturbance in Los Chimalapas. Rev. Biol. Trop. 62 (4): 1421-1432. Epub 2014 December 01.

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Ocelot *Leopardus pardalis* (Linnaeus, 1758) distribution ranges from the Southern United States to Northern Argentina (Murray & Gardner, 1997; Sunquist & Sunquist, 2002). It is found in a wide variety of habitats where it coexists with other cats such as the jaguar *Panthera onca* (Linnaeus, 1758), the puma *Puma concolor* (Linnaeus, 1771), the margay *Leopardus wiedii* (Schinz, 1821), and the jaguarundi *Puma yagouaroundi* (Lacépède, 1809) (Murray & Gardner, 1997; Sunquist & Sunquist, 2002; de Oliveira et al., 2010). Within these habitats, the ocelot can impact other species due to its role as a mesopredator or through

intraguild predation (Sunquist & Sunquist, 2002; de Oliveira et al., 2010). In areas where other large-size predators are absent, such as the jaguar and the puma, this species may become the primary predator.

Some studies indicate that ocelots prefer areas with closed canopy and avoid large open areas (López-González, Brown, & Gallo-Reynoso, 2003; Harveson, Tewes, Anderson, & Laak, 2004; Martínez-Calderas et al., 2011). The ocelot is mainly nocturnal, but in some areas exhibits day time activities (Ludlow & Sunquist, 1987; Caso, 1994). The birth rate is 1:1, the subadults occupy the natal area until

sexual maturity is reached, and take several months to occupy the permanent area as adults (Laak, 1991; Caso, 1994; Haines, Tewes, Laack, Grant, & Young, 2005). Diet varies throughout its distribution: prey <100g are more frequent, however medium-sized prey provide greater biomass (de Oliveira et al., 2010).

Ocelot population density varies considerably across its distribution (de Oliveira et al., 2010) and presents a significant relationship with latitude and precipitation. This relationship has enabled the generation of a density model (Di Bitetti, Paviolo, De Angelo, & Di Blanco, 2008a). Ocelot density has been calculated using radio telemetry data (Dillon & Kelly, 2008) and camera trapping (Maffei, Noss, Cuéllar, & Rumiz, 2005; Di Bitetti et al., 2008a). In camera trapping studies, estimates were made using capture-recapture data and demographically closed population models (Trolle & Kéry, 2003; 2005; Kolowski & Alonso, 2010; Díaz-Pulido & Payan, 2011; González-Maya & Cardenal-Porras, 2011). Nonetheless, demographically open population models are the most appropriate for long term research (>3 months) as these models allow for individual entry and exit to the population of interest over time by birth, death, immigration and emigration (Lebreton, Burnham, Clobert, & Anderson, 1992). Although this approximation has been employed in studies of felid populations (Gutiérrez-González, Gómez-Ramírez, & López-González, 2012), it has not yet been applied to ocelots.

Ocelot studies have been conducted in the Southern United States and in Central and South America. In Mexico, studies have been carried out in the Northern, Western, and central parts of the country in several habitat types, including dry tropical forest, submontane thornscrub, xeric shrublands and deciduous forest. Studies of Carnivora species in Southeast Mexico are few (Ceballos, Chávez, List, & Zarza, 2007; Torres, 2009), even though this region has a high concentration of biodiversity in Carnivora (Valenzuela & Vázquez, 2007). Moreover, this region is also covered by rainforest, which is

one of the most vulnerable habitats (Reyes, Mas, & Velázquez, 2010).

The region of Los Chimalapas is located in the Selva Zoque, Southeast Mexico, and it is one of the largest rainforest tracts in Mesoamerica (Salas, Schibli, & Torres, 2001). It stands out for having more than 300 000ha of semi-deciduous tropical forest and tropical rain forest and more than 40% of Mexico's vertebrates, nine (22%) of which are endemic to Mexico (Salas et al., 2001; Lira-Torres, Galindo-Leal, & Briones-Salas, 2012). Although the deforestation rate is low in Los Chimalapas, constant change in the forest cover is increasing, mainly in areas near water bodies and villages, but it is unknown if these areas are used by the species. Additionally, constant alterations can generate changes at the community or population levels. Given these modifications, it is convenient to conduct studies on the abundance of species in these environments and their trends over time. Ocelots are particularly important due to their ecological role within the felid assemblage as a mesopredator, however their population status and spatial distribution in this region are unknown. This ocelot ecology study aims to contribute with information on population density, activity patterns, sex ratio, residence, and spatial distribution in Los Chimalapas.

MATERIALS AND METHODS

Study Site: San Antonio Nuevo Paraíso is located in the Northern part of Los Chimalapas (17°09'42" N - 94°21'20" W), in the municipality of Santa María Chimalapa. Its vegetation includes tropical rain forest and chaparral. The regional climate is hot and humid, with annual temperatures ranging from 22 to 26°C, and an annual precipitation of 2 000 to 2 500mm (Trejo, 2004). The wet season lasts from June to December and the dry season from January to May. San Antonio Nuevo Paraíso has 140 inhabitants with cornfield and livestock areas.

Data collection: From March 2011 to June 2013, 29 sampling stations were installed, 22 of them equipped with one camera trap, and seven

with two cameras operating independently. Traps were located on both sides of the trail in order to obtain images of both flanks of the animals so as to recognize them in subsequent shots (Trolle & Kéry, 2003; Di Bitetti, Paviolo, & De Angelo, 2006). Un-baited traps were placed at a height of 30cm above ground, in the rainforest adjacent to rivers (three traps), inside the forest (14), on trails (four), and in areas adjacent to livestock (five). Because of the particular topographic conditions of Los Chimalapas, and as the minimum home range of a male (3.5km²) includes two or three females (Sunquist & Sunquist, 2002), traps were spaced from 0.5 to 1.5km apart. The initial model was Wildgame IR4 4MP Digital Game Scouting Camera, and traps that failed were replaced by a ScoutGuard SG550/SG550V 5MP and a Bushnell Trophy Cam 5MP; 100% of the initial traps were replaced during the study. All traps were programmed to stay active 24h. The delay period between photographs was set to 1min.

A preliminary filter was applied to avoid data duplication (Di Bitetti et al., 2006; Monroy-Vilchis, Zarco-González, Rodríguez-Soto, Soria-Díaz, & Urios, 2011). For abundance calculations, all photographs taken by a trapping station during a 24h period constituted a single independent record. Individual identifications were made according to spot patterns (Trolle & Kéry, 2003). Due to a lack of photos of both flanks for each individual, analysis was based on the flank with the greater number of records. A capture-recapture history was built for each identified ocelot: their presence was established monthly and each month was considered a sampling occasion. Ocelot abundance was obtained using the Cormack-Jolly-Seber (CJS) open population model. Closed-population assumptions were evaluated with CloseTest (Stanley & Richards, 1999) and the CJS model assumptions with U-CARE (Choquet, Lebreton, Gimenez, Reboulet, & Pradel, 2009).

The CJS model assumes that each capture is an independent event, that capture and survival probabilities at a single capture occasion are the same for all animals, that capture and survival probabilities are equal across time

intervals, and that any emigration is permanent (Lebreton et al., 1992; Lindenmayer, Lacy, & Viggers, 1998). This model only includes two parameters: survival probability (Φ) and capture probability (p), whereas the original Jolly-Seber model allowed for the estimation of apparent survival rates, capture rates, population sizes, and the number of new animals (Pollock, 1982), consequently the CJS model provides greater accuracy in the estimations (Lindenmayer et al., 1998). The survival probability and the capture probability can vary or remain constant over time. The candidate models were: (1) constant Φ and p , [Φp]; (2) constant Φ and p varying through time (expressed in year: 2011, 2012, and 2013), [Φp_t]; (3) Φ varying over time and constant p , [$\Phi_t p$]; and (4) both Φ and p vary over time, [$\Phi_t p_t$] (Lebreton et al., 1992). The best model was selected using the Quasi-Akaike Information Criterion (QAIC; Burnham & Anderson, 2002). Model parameters were adjusted to minimize overdispersion due to extrabinomial variation, by dividing the observed value of c -hat from the original data by the mean of the simulated values of c -hat from 1 000 pseudo-samples generated through the bootstrap parametric method (Santos-Moreno, Briones-Salas, & López-Wilchis, 2007). The program Mark 6.0 was used to run model construction and analysis (Cooch & White, 2012). Once the final model was selected, population size (N) was calculated as the number of observed individuals divided by the capture probability (Lindenmayer et al., 1998).

In order to estimate the effective sampling area, we calculated the minimum convex polygon area defined by all trapping stations plus a buffer size. As there is still debate about the calculation of buffer size for an effective sampling area (Maffei et al., 2005; Trolle & Kéry, 2005; Dillon & Kelly, 2008; Maffei & Noss, 2008), we used both the mean maximum distance moved by ocelots caught on two or more occasions (MMDM), and half the MMDM ($\frac{1}{2}$ MMDM). The variance of area was estimated follow Karanth and Nichols (1998). Density was calculated as the estimated number of

individuals by the CJS capture-recapture model divided by the effective sampling area, and extrapolated to a 100km² area.

Due to the close distance between the traps, it was important to evaluate whether the observed camera trap captures at one site was independent on the neighboring sites. So, we used Moran Index (I) to evaluate spatial autocorrelation (Sokal & Oden, 1978) in the camera trap captures. Under the null hypothesis of no spatial autocorrelation, Moran's I has the expected value approaching zero in absence of autocorrelation, with positive and negative values indicating positive and negative autocorrelation, respectively. The tests were using ArcGis 9.3 (Esri, 2008); the inverse distance was used for the computations.

In order to describe activity patterns, all photographs taken by each sampling station within a 1h span were considered as a single record (Di Bitetti et al., 2006). The 24h were grouped into one-hour periods, and each photographic record was classified within those intervals. The diurnal activity lasted from 6:00am-20:00, and the nocturnal from 20:00-06:00. Circular techniques (Zar, 1999) were used to analyze whether nocturnal and diurnal activity varied significantly through the seasons. We first tested if activity differed from day and night for each season per year. The activity between dry and wet seasons was then compared. The Mardia-Watson-Wheeler test was used to test if activity varied between seasons, and the Watson U² test was applied if the observations were less than 10. Statistical tests were performed with the software Oriana version 4 (Kovach Computing Services, 2011), and the significance of the test was $p \leq 0.05$.

To estimate the sex ratio, each identifiable individual was classified into male (testicle presence) and female (without testicle presence). The ratio was expressed as the number of males per female (male:female). A binomial test was performed to determine if the ratios differed significantly from a 1:1 ratio, and the test was significant at $p < 0.05$. We counted the period of residence of each individual as the

number of months from the first capture to last re-capture.

A Multiple Discriminant Analysis was used to determine which of the selected environmental variables best explains ocelot abundance in the region. The response variable was the number of ocelot records, which were grouped into three record classes: 1=zero record; 2=from one to four records; and 3=more than five. The predictor variables were the following: distance from water bodies (DWB); distance from nearest village (DNV); distance to cornfields and livestock (DCP); altitude (ALT); number of prey records (PR) for each camera trap location; and, habitat (HAB). The habitat was classified as 1=livestock; 2=trail; 3=rivers; and 4=inside the forest. Distances were measured in kilometers, and altitude in meters. Prey species considered had a weight of ≤ 10 kg. All values were standardized by dividing each value by the respective variable's maximum. Spatial data from variables was calculated using ArcGis 9.3 (Esri, 2008; Inegi, 2000), and statistical analyses with Statistica 7 (Statsoft, 2005), and NCSS 2007 (Hintze, 2010).

RESULTS

The total sampling effort was 8 529 trap-days; 543 pictures were of the order Carnivora, of which 128 were ocelots, representing 103 individual records. From the 103 ocelot photographs, 33 could not be identified to an individual level because of poor photograph quality, lighting or position of the animal. From the remaining 70, 34 were right-side pictures, enabling the identification of nine individuals (Table 1); 36 left-side pictures were obtained, with five identified individuals. Two individuals were identified from both sides. Thus, the capture-recapture history matrix was built with right-side picture data, but adding the data of identified individual for both sides, so that the number of records was 57.

The ocelot population was not closed ($\chi^2=223.47$, d.f.=20, $p=0.000$). There were no additions ($p=0.99$), however there were population losses ($p=0.00$). As for the CJS model

TABLE 1
Capture-recapture history, sex, and residence time of the nine ocelots in Los Chimalapas, Mexico

Individual	Sex	Residence Time	Capture-recapture history
H1	Female	12	0000000010000000110100000
H2	Female	10	0000010000001010000000000
H3	Female	1	1000000000000000000000000
M1	Male	23	0101100011111111111101110
M2	Male	16	0000001000000111100001000
M3	Male	1	0000100000000000000000000
M4	Male	1	0000100000000000000000000
M5	Male	1	0010000000000000000000000
NC1	NC	1	00000000000000000000100000

The presence was established monthly and, each month was considered a sampling occasion. 0=no capture, 1=capture, NC=no cataloged.

TABLE 2
Values for CJS capture-recapture model generated by ocelot population estimates in Los Chimalapas, Mexico

Model	QAICc	Delta QAICc	QAICc weight	Number of Parameters	Qdeviance
$p\Phi_t$	120.71	0	0.75	4	111.37
$p_t\Phi_t$	123.81	3.10	0.16	6	108.81
$p\Phi$	125.34	4.63	0.07	2	120.96
$p_t\Phi$	128.41	7.70	0.07	4	119.08

p =capture probability; Φ =survival probability; QAICc=Quasi-Akaike Information Criterion; Delta QAICc=AICc difference between respective model and best model; QAICc weight=relative contribution of each model regarding the sum of models; Qdeviance=degree of discrepancy between model and data. \hat{c} =0.883.

assumptions, neither the presence of transiting individuals ($p=0.24$) nor the camera trap effects in mark and capture history ($p=0.30$) were significant. Camera-trap captures were spatially independent in total captures (Moran $I=-0.024$, $p=0.97$), captures in 2011 ($I=-0.015$, $p=0.95$), 2012 ($I=0.062$, $p=0.75$), and 2013 ($I=-0.475$, $p=0.23$).

After adjusting parameters with the over-dispersion correction factor ($\hat{c}=0.88$), the best model was $[\Phi_t, p]$, supported by 75% of the data. The second best model was $[\Phi_t, p_t]$, supported by 16% of the data (Table 2). According to the best model, estimate abundance was 20.13(SE=0.08). There were five individuals in two or more trap locations, with an average maximum distance traveled of 2.6km, so density was 38 individuals/100km² (95% Confidence Interval=29-56) with 1/2MMDM,

and 22 individuals/100km² (95% Confidence Interval=17-32) with MMDM (Table 3).

We obtained 104 independent records from which to describe activity patterns. The ocelot was more active at night, but it also showed diurnal activity throughout the study period. Maximum activity occurred between 1:00-6:00 (Fig. 1). The differences between nocturnal and diurnal activity in each period were significant ($p<0.05$) and so a separate analysis was carried out. Because within each season (dry or wet) the differences between years (2011, 2012 and 2013) for nocturnal (U^2 of the Watson test_{wet season}=0.051, $p>0.5$; U^2 _{dry season}=0.138, $p>0.1$) or diurnal activity (U^2 _{wet season}=0.057, $p>0.5$; U^2 _{dry season}=0.029, $p>0.5$) were not significant, the data between years was pooled as a single sample in final analysis. The differences in nocturnal activity between the wet and dry

TABLE 3
Abundance and ocelot density (individuals per 100km²) obtained by CJS model, including parameters related to its calculation

Abundance (SE)	Density(CI)	Total area	Buffer(SE)	p(SE)	ϕ (SE)
20.13(0.08)	38(29-56)	52km ²	½MMDM=1.3km(0.8)	0.44(0.07)	Φ_{2011} 0.65(0.14)
	22.6(17-32)	89Km ²	MMDM=2.6km(0.8)		Φ_{2012} 0.99(0.02)
					Φ_{2013} 0.78(0.16)

Best CJS model was $p\Phi_i$; n=9 individuals; p=capture probability; Φ_1 to Φ_3 =survival probability during each of the three years. CI=95% Confidence Interval.

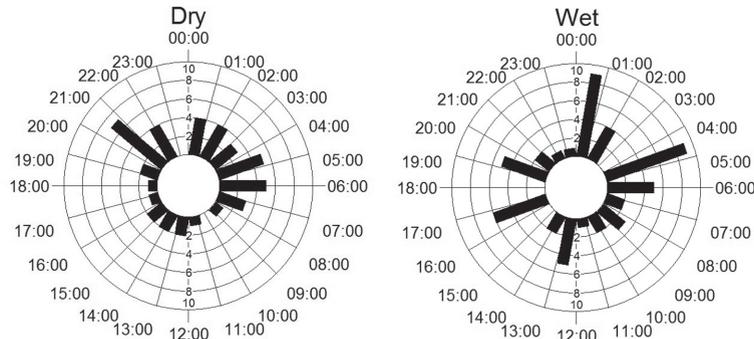


Fig. 1. Ocelot activity patterns for the wet and dry seasons in Los Chimalapas, SE Mexico.

seasons were not significant (W of the Mardia-Watson-Wheeler test=1.047, $p=0.59$) and the differences in diurnal activity between the two periods were not significant ($W=0.37$, $p=0.83$).

Three females and five males were recorded, and one individual was not classified. The sex ratio was 1:0.6, but it was not significantly different from 1:1 ($z=0.35$, $p=0.72$). Regarding presence, five of nine ocelots (55%) were observed during a single month, one for 10 months, one for 12, one for 16, and one for 23 (mean=7.33, 95% confidence interval from four to 10 months) (Table 1).

Discriminant Function 1 explained 71% of total variance. The most important variable was the proximity to the village and, for the Discriminant Function 2, the number of prey records. Both functions show a tendency for trap grouping in function of ocelot abundance classes, particularly in discriminating the sites without ocelot records (Fig. 2). Stations with the highest number of ocelot records showed a high number of prey records (mean=58.3)

and were 3-6km from the village. In contrast, stations without ocelot records showed a low value of prey records (mean=3.4) and were 5-8km from the village (Table 4).

DISCUSSION

The estimated ocelot population density in Los Chimalapas was 38individuals/100km². This density was within the range of 6 to 106 individuals/100km², observed in the tropical deciduous forest, tropical oaks forest or subtropical thornscrub in the North and Center of Mexico (López-González et al., 2003; Martínez, 1997). In other rainforests in Southeast Mexico, the density was 14 individuals/100km² (Torres, 2009), so, the density in Los Chimalapas was higher. In other eco-regions such as Los Llanos in Venezuela, the Pantanal in Brazil or the dry forest in Bolivia, the calculated density was from 11 to 59individuals/100km² (Ludlow & Sunquist, 1987; Maffei et al., 2005;

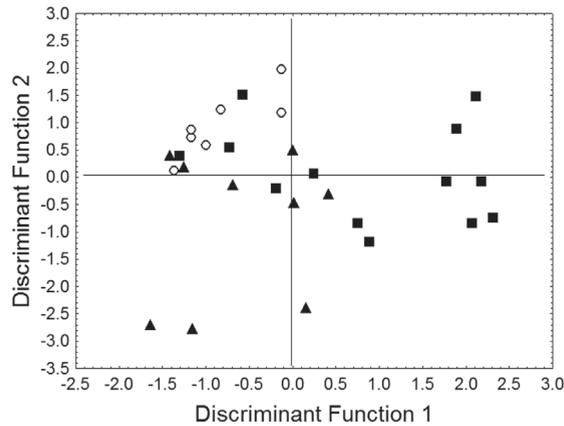


Fig. 2. Dispersion graph for ocelot abundance class over the two discriminant functions. The variable for Discriminant Function 1 was the nearness to the village, and for Discriminant Function 2 was the prey record. Circles=0 records; square=1 to 4 records; triangles=more than 5 ocelot records.

TABLE 4

Discriminating Function (DF) values, standardized canonical coefficients, and the means of the original variables

Variable	Means			Total range	Standardized Canonical Coefficients	
	Group 1	Group 2	Group 3		FD 1	FD 2
HAB	4*	1 and 4*	2 and 4*		-0.515	0.229
DWB	0.63(0.4)	1.44(1.1)	0.53(0.4)	0.09-3.03	0.329	-0.108
DNV	6.69(1.0)	4.01(2.3)	4.88(1.5)	0.37-8.19	-0.681	-0.505
DCP	1.86(1.1)	1.36(0.8)	1.08(0.6)	0.24-3.13	0.462	-0.281
ALT	330(120)	396(147)	332(132)	138-674	0.509	-0.600
PR	3.43(3.9)	25(29)	58.3(86.9)	0-254	-0.033	1.007
Ocelot records	0	1.46(0.78), n=19	9.33(6.76), n=85			
	Eigenvalue	% of total explained variance	Canonical Correlation			
FD1	0.716	61.5	0.64			
FD2	0.449	100	0.55			

Variable value (Standard Deviation). Abundance class: Group 1=0 records, group 2=1-4 records, group 3=5 or more records. HAB=habitat; DWB=distance from water bodies, DNV=distance from nearest village, DCP=distance to cornfields and livestock areas; ALT=altitude; PR=medium sized preys records. *the location traps was in 1=livestock, 2=trail, 3=river, and 4=inside the forest. Distances were measured in kilometers and altitude in meters.

Trolle & Kéry, 2003; 2005; Díaz-Pulido & Payan, 2011), and in other similar rainforests in the Americas, densities were from 8 to 75 individuals/100km² (Di Bitetti et al., 2006; 2008a; Kolowski & Alonso, 2010; González-Maya & Cardenal-Porras, 2011). Therefore, the population density observed in Los Chimalapas is neither high nor low in comparison with these regions.

The capture-recapture models for closed populations are widely used in the estimation of ocelot population size, but until now, the open population models had not been used for this species. Open population models are the most appropriate choice when studies are carried out over a longer time period, when populations show additions and/or losses, such as the ocelot population in Los Chimalapas,

something which is not considered in closed population models (Lebreton et al., 1992). Despite the distance of the traps, captures were spatially independent and model assumption was not violated. The CJS model can produce biases in the parameter estimation due to the violation of the other assumptions (equal probabilities of capture and survival, and the permanence and migration) because there were variations between individuals in terms of age, sex, or migration of the ocelot (Laak, 1991; Caso, 1994). Open population models allow us to observe variations in certain parameters over time (Gutiérrez-González et al., 2012). Thus, this model is a suitable tool for the study of populations that require long-term monitoring, and it is useful for the implementation of effective strategies for carnivore conservation in the region.

It has been observed in previous studies that the ocelot density is high in ecoregions near the Equator and with high rainfall. The generated model indicates that ocelot densities decrease with latitude and increase with rainfall (Di Bitetti et al., 2008a). The CJS model estimation was consistent with patterns of abundance according to this model: 37 to 56 individuals/100km² using the model of latitude and precipitation, respectively. So, the geographic location of Los Chimalapas may be a determining factor in ocelot density. Los Chimalapas is considered a well-preserved region: about 90% of the forest is conserved and the presence of human activity and the proportion of livestock areas are low (Ortega del Valle, Carranza, & Martínez, 2012). The ocelot density tends to be higher in better preserved areas than in those exposed to human activity: 20-56 compared with 11 individuals/100km², respectively (Trolle & Kéry, 2003; Di Bitetti et al., 2006).

The region has a significant variety of potential prey species, but there is no data on ocelot diet in the area. However, studies in rainforests in Central and South America indicate that small mammals are most common in the ocelot diet, but that the Central American agouti *Dasyprocta punctata* (Saussure, 1860) and the

paca Cuniculus paca (Linnaeus, 1776) are also important in terms of biomass and frequency (Moreno, Kays, & Samudio, 2006; de Oliveira et al., 2010). These species are present in Los Chimalapas with high relative abundances: about 19% of total records were for these two species (G. Pérez, in prep.). In surrounding areas, the *C. paca* population was high, in comparison to other area: 67-70 individuals/100km² (Parroquin, Gallina, Aguirre, & Pérez, 2010; Santos-Moreno & Pérez-Irineo, 2013). This prey species constitute a food base able to sustain predator populations, such as the ocelot. In other habitats, the density of predators like the tiger *Panthera tigris* (Linnaeus, 1758; Karanth, Nichols, Kumar, Link, & Hines, 2004), the jaguar (Polisar et al., 2003), and others (Carbone, Pettorelli, & Stephens, 2011) was positively correlated with prey density.

Sex ratio in the ocelot population of Los Chimalapas was 1:1. In contrast, in South American populations, the number of females was greater than that of males (Ludlow & Sunquist, 1987; Di Bitetti et al., 2006). The males move more widely, for the search of an available home range, the defense of territory, or for the reproduction, so that they were recorded more frequently (Laak, 1991; Caso, 1994). While no offspring or young were found during the study period, one of the identified females was pregnant during the dry season of 2011, suggesting that the ocelot population was reproductive.

The population seems to include an important percentage of transient individuals; 50% of identified individuals were observed in the area only during a single month, and only two individuals remained in the area for more than 16 months. Based on other wide studies (>2.5 years), young ocelots disperse and establish a home range after the 14-35 months of age (Laak, 1991; Haines et al., 2005; Mares, Moreno, Kays, & Wikelski, 2008). Due to the duration of this study (27 month), there is some uncertainty as to the classification of these two individuals as residents, however it also provides insight into this parameter in the ocelot population in the area. The transient individuals

could have migrated to other areas, such as Sierra Tres Picos, in Central Los Chimalapas or as the Uxpanapa region in Veracruz. Both regions are important flora and fauna preservation areas (Salas et al., 2001).

In Los Chimalapas, the ocelot showed primarily nocturnal activity. However, the diurnal activity was present throughout the study period. In several studies, the ocelot activity was primarily nocturnal (18:00-6:00), with little diurnal activity (Ludlow & Sunquist, 1987; Emmons, 1988; Maffei et al., 2005; Di Bitetti et al., 2006). In other studies, 38% of the activity was diurnal (Caso, 1994). The amplitude of the activity pattern recorded in Los Chimalapas may result from two factors: the availability of prey both day and night, and low human activity and poaching in the area.

Although the paca's activity pattern is variable throughout its distribution, in San Antonio Nuevo Paraíso the species was nocturnal (Gregorio, 2012); whereas the agouties were diurnals (G. Pérez, in prep.). The relationship between mesopredator activity and prey has been observed in other studies (Ludlow & Sunquist, 1987), as well as for other predator species such as the puma, the jaguar and the tiger (Paviolo, Di Blanco, De Angelo, & Di Bitetti, 2009; Harmsen, Foster, Silver, Ostro, & Doncaster, 2011).

On the other hand, human presence was scarce in the area and poaching was only for local consumption, therefore, the ocelot was active without the risk of being hunted and their activity was wider than in other regions. In the Yucatan Peninsula, Mexico, the ocelot activity was nocturnal (Torres, 2009). In this region, the climatic conditions are similar to Los Chimalapas, but with a long history of disturbance. In regions where the ocelot is hunted, its activity is completely nocturnal (Sunquist & Sunquist, 2002). It can thus be established that the quality of the region and the presence of prey determine activity rather than the physical conditions. In other species, the activity amplitude was also less in areas with human activity. Pumas show activity during both periods of the day in areas or seasons with low poaching;

on the other hand, they were mainly nocturnal in areas with high poaching (Paviolo et al., 2009). In canids, the activity shifts as a strategy to avoid human contact (Kitchen, Gese, & Schauster, 2000). This same pattern was observed in cat's larger prey in other regions (Di Bitetti, Paviolo, Ferrari, De Angelo, & Di Blanco, 2008b).

In this study, the proximity to the water supply and livestock areas does not seem to affect the ocelot presence, probably due to the abundance of water in the region. Perhaps on a larger scale this effect would be different, as with other felids (Hatten, Averril-Murray, & Van Pelt, 2003; Monroy-Vilchis, Rodríguez-Soto, Zarco-González, & Urios, 2009). In contrast, ocelot spatial distribution was positively affected by the proximity to the village and the greater amount of prey. No vehicular traffic exists in the region, and pressure of human activities is considered low. So, the ocelot occupies different areas without the risk of vehicular collision or poaching.

In Los Chimalapas, potentially useable areas for livestock were used by the ocelot, such as areas near the village. These areas have dense vegetation cover, but if vegetation cover is reduced, the ocelot would avoid them. The ocelot supports some degree of disturbance, but they are dependent on dense cover (Sunquist & Sunquist, 2002; Harveson et al., 2004; de Oliveira et al., 2010). An increase in open areas would negatively affect the ocelot movement and dispersion routes (Haines et al., 2005; Harveson et al., 2004; Grigione et al., 2009) and consequently the ocelot distribution pattern. This species occupies a wide range of microhabitats and uses trails and roads, indicating a wide ecological plasticity (Murray & Gardner, 1997; Sunquist & Sunquist, 2002).

The ocelot is listed as an endangered species by Mexican law (Semarnat, 2010); it is among the ten species with the highest conservation priority in the country (Valenzuela & Vázquez, 2007). In Los Chimalapas, the ocelot population enjoys ecological and environmental conditions that favor its presence in the mid and long term. However, changes in

vegetation cover will affect the ocelot population, activity and, distribution in the long-term. Thus, it is important to continue long-term ecological studies on different species and their possible population shifts with appropriate analytical tools.

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RESUMEN

Densidad, distribución y actividad del ocelote *Leopardus pardalis* (Carnivora: Felidae) en los bosques húmedos del sureste mexicano. El ocelote *Leopardus pardalis* es importante en comunidades terrestres debido a su papel ecológico dentro del grupo de felinos de tallas pequeñas y como mesodepredador. A pesar de la disminución del hábitat del ocelote en el sureste de México, son pocos los estudios ecológicos. El siguiente trabajo presenta una contribución de algunos aspectos ecológicos de la especie en esta región. Se estimó la densidad poblacional, patrón de actividad, proporción de sexos, tiempo de residencia y distribución espacial del ocelote. El estudio se llevó a cabo mediante fototrampeo dentro de Los Chimalapas, en el estado de Oaxaca, sureste de México. Se establecieron 29 estaciones dentro de la selva alta y se cubrió un área de 22km², durante dos años (marzo 2011-junio 2013). La densidad fue estimada usando Modelos de Captura-Recaptura para poblaciones demográficamente abiertas, las técnicas circulares fueron usadas para determinar si la actividad nocturna y diurna varió significativamente entre épocas y, un análisis discriminante múltiple fue usado para conocer cuáles variables explican mejor la abundancia del ocelote en la región. Se obtuvieron 103 registros de ocelote con un esfuerzo de 8 529 días-trampa. Se estimó una densidad de 22-38 individuos/100km². La población del ocelote tuvo un porcentaje alto de transeúntes (55%) y la proporción de sexos fue estadísticamente similar de 1:1. El ocelote estuvo más activo en la noche (1:00-6:00am), pero exhibió

actividad diurna durante todo el periodo de estudio. La distribución espacial estuvo afectada positivamente por la proximidad a poblados y por la cantidad de presas. La población del ocelote parece estable, con una densidad similar a otras regiones de Centro y Sudamérica, quizá debido a la diversidad de especies presa y al grado bajo de alteración en Los Chimalapas.

Palabras clave: captura-recaptura, fototrampeo, Los Chimalapas, Modelo CJS.

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